# OKLAHOMA STATE UNIVERSITY SCHOOL OF ELECTRICAL AND COMPUTER ENGINEERING



## ECEN 3723 Systems I Spring 2003

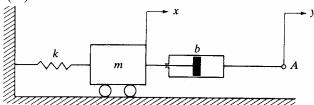


#### **Final Exam**

1)	; 2)	; 3)	; 4)	;
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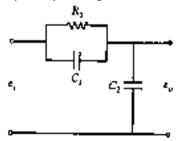
#### Problem 1: (Time Response)

The mechanical system shown below is at rest initially. At t = 0, a unit-step displacement input is applied to point A (i.e., y(t) = u(t)). Assuming that the system remains linear throughout the response period and is *overdamped*, determine the response x(t) as well as the values of x(0+),  $\dot{x}(0+)$  and steady state  $x(\infty)$ .

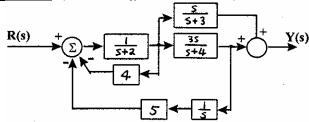


# **Problem 2**: (Frequency Response)

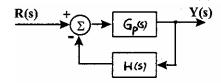
Consider the stable electrical circuits shown below. Assume that the input is sinusoidal,  $e_i(t) = E_i \sin \omega_1 t \cos \omega_2 t$ , determine the steady state output voltage  $e_o(t)$ .



## **Problem 3**: (Block Diagram Reduction)



Use block diagram reduction to rearrange the above block diagram into the form shown below and find its transfer function,  $\frac{Y(s)}{R(s)}$ .



## **Problem 4**: (Routh Stability Criteria)

Find the region of K in  $G_p(s)$  for which the unity feedback (i.e., H(s) = 1) control system is stable

$$G_p(s) = \frac{K(s^2 + 15s + 55)}{s(s^2 + s + 10)}$$
.

# <u>Problem 5</u>: (Analogous System)

Using the force-current analogy, derive an analogous electrical circuit from the mechanical system shown below, where p(t) is the force input to the system.

